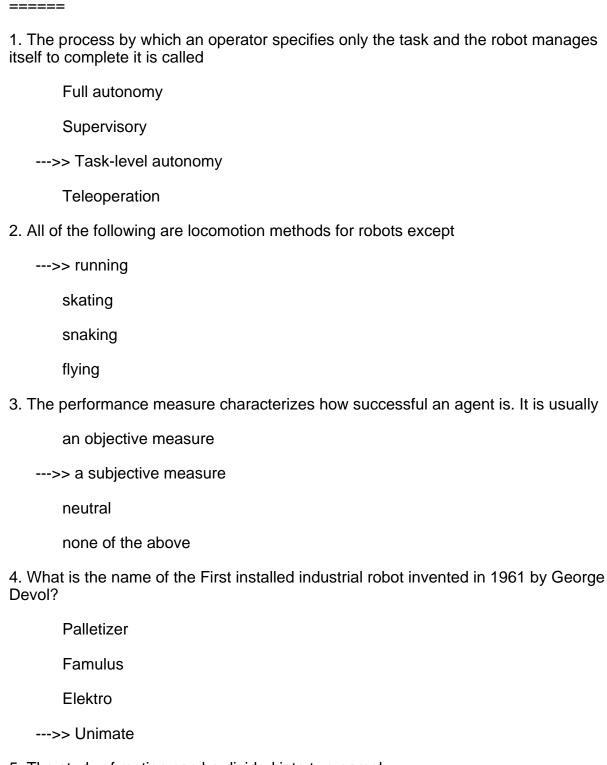
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5. The study of motion can be divided into two namely

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mechanics and dynamics

--->> kinematics and dynamics none of the options 6. The science and technology of machines that see Sensing --->> Vision **NLP** none of the options 7. An operation involving an Effector is called Actuator --->> Action Sequence Percept _____ refers to the opposite case in which required joint values are calculated for given end effector values, as done in path planning inverse mechanics --->> inverse kinematics inverse dynamics none of the options 9. GIGO stands for Gamble in, Gamble out --->> Garbage In, Garbage Out Good in, Good out none of the options

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Task-level autonomy

Supervisory

--->> Teleoperation

Full autonomy

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