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conditional probability measure on (ω) , then we say that $((\omega, A, P))$ is the probability space obtained by conditioning $((\omega, A, P))$ by the event B

[STT311] In general, if an event B depends on occurrence of events, $(A_1, A_2,, A_n)$. Then
$\label{eq:continuity} $$ \C(P(B)=\sum_{i-1}^{n}P(A_i)P(\frac{B}{A_i})) $$$
[STT311] A probability measure P on a field of subset A of set \(\omega \) is a real-valued function having domain A satisfying the property\(\text{P (\omega)} = 1\)
[STT311] Let \(\left [A_n \right]\) be a sequence of independent measurable sets. If \(\sum_{i=1}^{\infty }P(A_n)=\infty \), then \(P(A_i)=0\)
[STT311] A random variable is a function whose domain of definition is the simple space S of a random and whose range is a set of real numbers. experiment
[STT311] Given that probability $P(a < x < b)$ defined as $P(a \le x \le b) = \int_{a}^{b} f(x dx)$, the function f is called theProbability function of X continuous
[STT311] The sample space denoted by \(\Omega \) is the collection or totality of all possible outcomes of a conceptual experiment
[STT311] The class of all events associated with a given experiment is defined to be the event space
[STT311] Let x be a random variable whose image set (S) is a continuous numbers such as an interval. Then the set \(a\leq x\leq b\) is anin S event
[STT311] If an event B depends on occurrence of event (A_1) or (A_2) , then
$\sqrt{(P(B)=P(B \land A_1) + P(B \land A_2))}$

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